

SV5100 Installation Software User's Manual

Version 3.1

MAR. 2013

Release Note

V1.2

- *Add "Live" page
- * Add "Replay" page
- * New: Tracking options setup
 - 1. Horizon Weight Trigger Tracking
 - 2. Dynamic mask

V1.3

- * New: Add 2 GPIs trigger pre-set positions function.
- * New: Add 16 sets of preset position triggered by RS485. The Protocols are compatible with Pelco-D.
- * New: Add a reboot button to remotely reboot SV2018 from power-off.
- * Modify Horizon Weight Setting (1~4), default is 3.
- * Indicate the latest log block.
- * Simplify the display of Version (i.e. 1.3 NTSC/PAL)
- * Add a Cancel button to cancel the transmitting between SV2018 and PC.
- * Notify the user when the SV2018 firmware is older than PC software (V1.3).
- * Enable 2 cameras live display even if the SV2018 RS485 is not connected
- * Add the default parameter setting.
- * Increase the speed of the mouse click event at calibration page.
- * Add double click function for default positions.

V3.0

- * Support SV3018 only

V3.1

- * Support SV2018, SV3018, SV4018

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1 Introduction of Product

IGUANA Active Tracking Surveillance System, a next generation and revolutionary camera developed by Sunvision Scientific Inc, combines the advantage of the panoramic lens cameras and the telescopic lens cameras

Motion detection has been used in many places in the current market. When a moving target is detected, traditional (dumb) security cameras can only sound the alarm, and passively waiting for a security guard, if any is available, to take the proper action.

The IGUANA system can actively track down the moving target and take the close up images of the target. By using masking techniques, IGUANA allows you to set region of interest within the panoramic view. The IGUANA system has dramatically improved the effectiveness of surveillance systems to meet the ever increasing demands of the security world.

Glossary:

SV2010: Installation kit for setting up SV2018 and SV4018.

SV2018: Analog (NTSC/PAL) IGUANA camera module.

SV3018: Network IGUANA camera module.

SV4018: HD-SDI IGUANA camera module.

SV5100: PC base software tool for installing & optimizing IGUANA camera module.

2 IGUANA System

2.1 SV2018 Configuration

SV2018 has two analog (NTSC/PAL) outputs, a wide angle view and a telescopic view. It can connect to any devices that are compatible with NTSC/PAL. SV2018 can also be used as a Speed-Dome mode with build-in RS-485.

SV2010 installation kit and SV5100 installation software are required for first time installation and calibration.

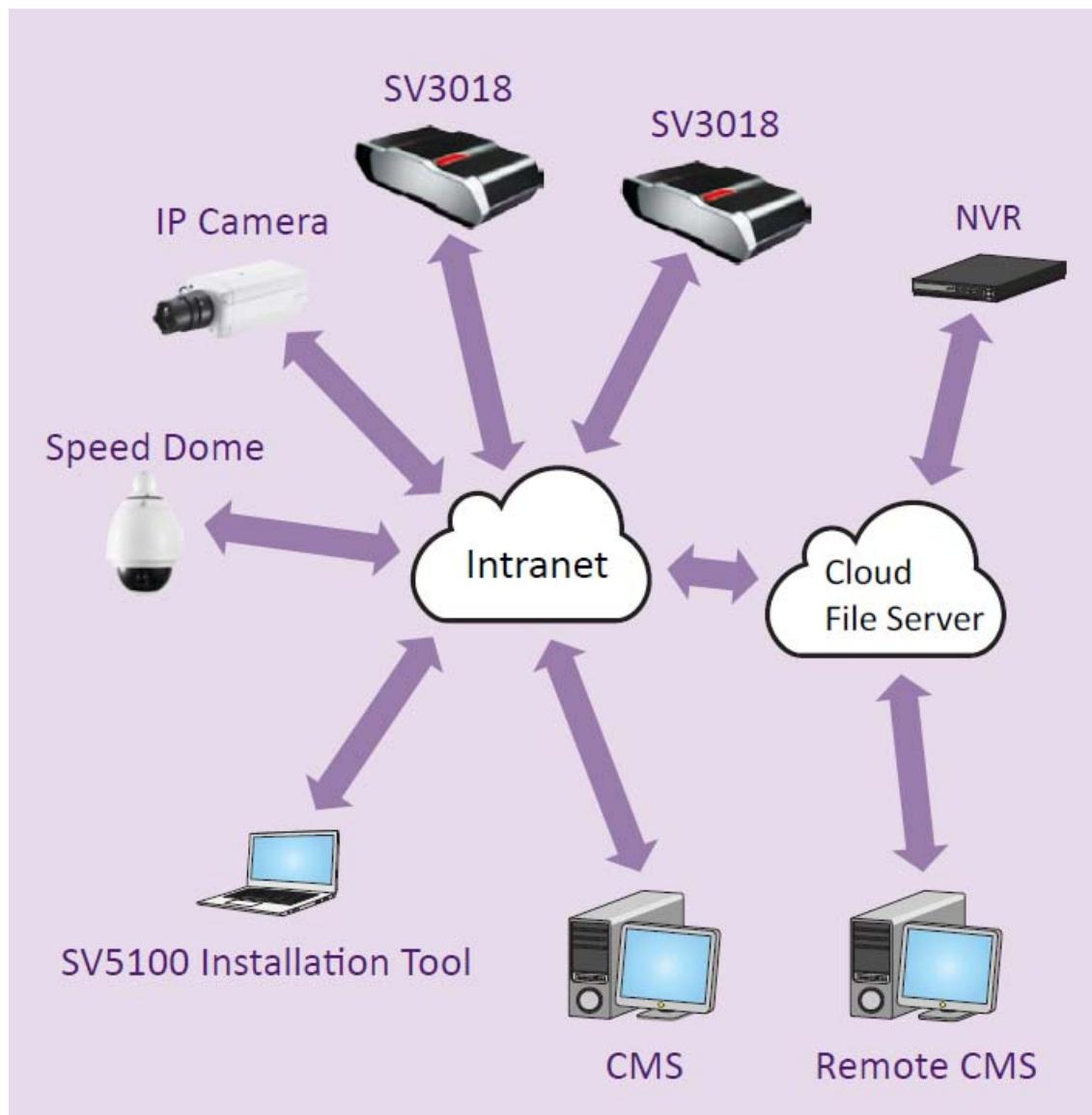


2.2 SV3018 Configuration

SV3018 is an IP base camera system. It integrates two Onvif conformant Mega-Pixel IP cameras and one IP base control unit.

Each SV3018 consumes 3 IP, two network cameras and a control unit.

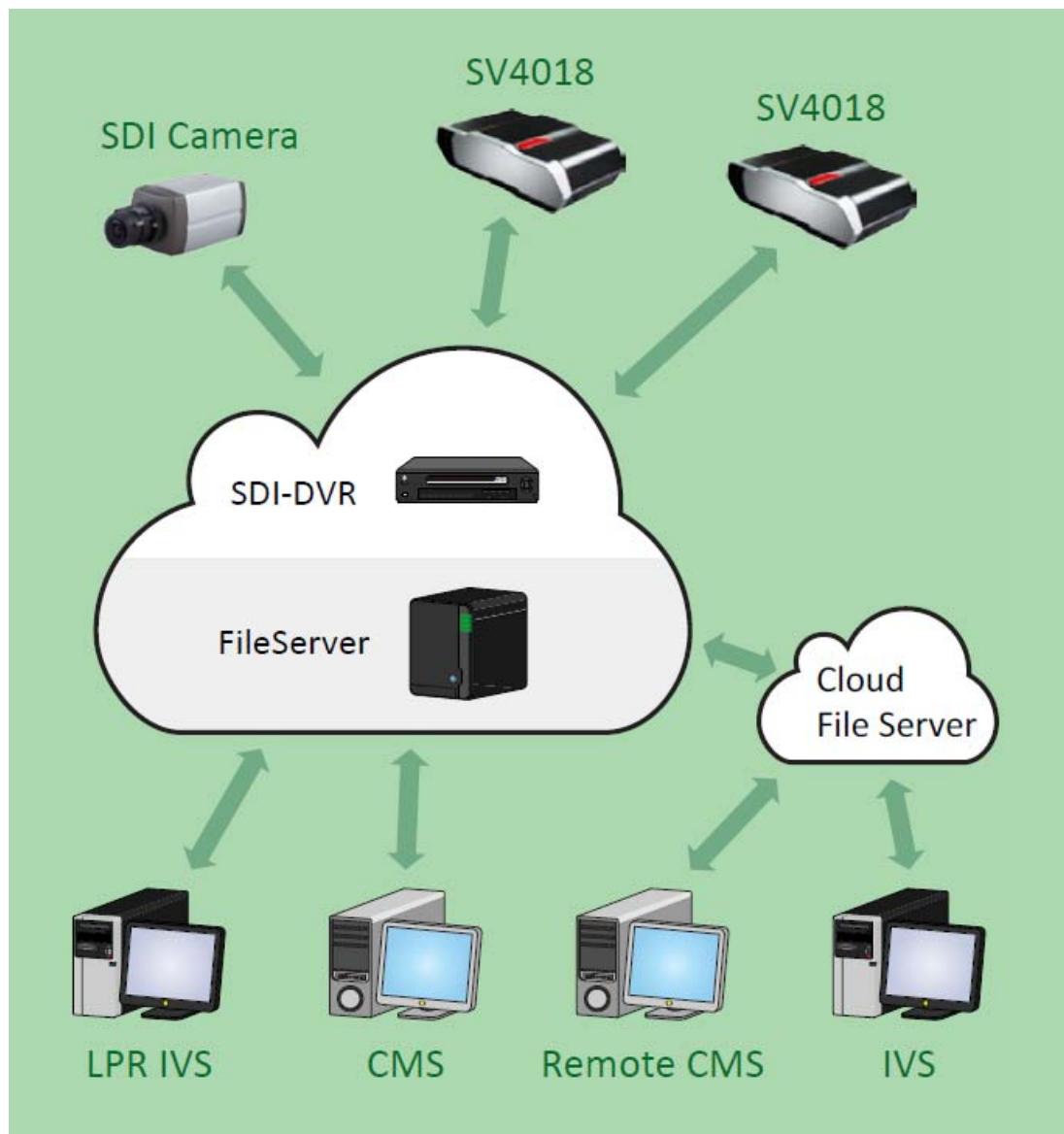
SV5100 installation software is required for first time installation and calibration.



2.3 SV4018 Configuration

SV4018 has two HD-SDI outputs, a wide angle view and a telescopic view. It can be integrated with any HD-SDI CCTV DVR or PC-base HD-SDI video capture surveillance system.

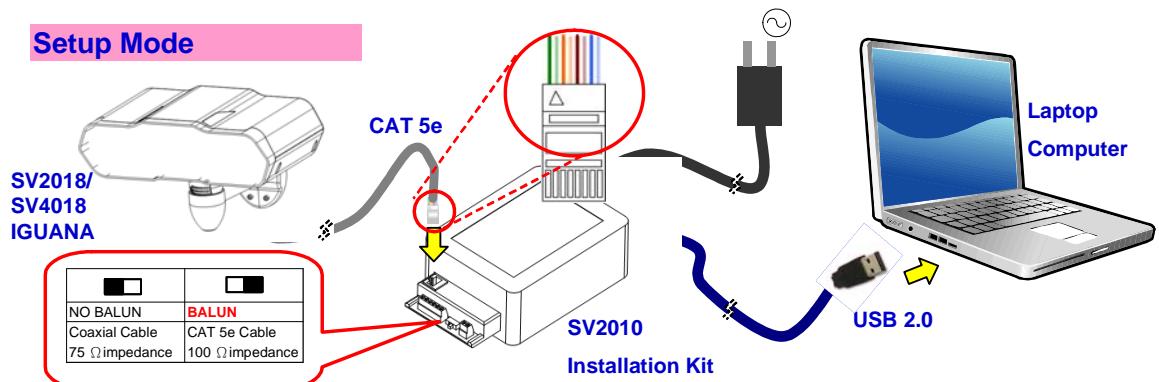
SV2010 installation kit and SV5100 installation software are required for first time installation and calibration.



3 How to Use SV5100

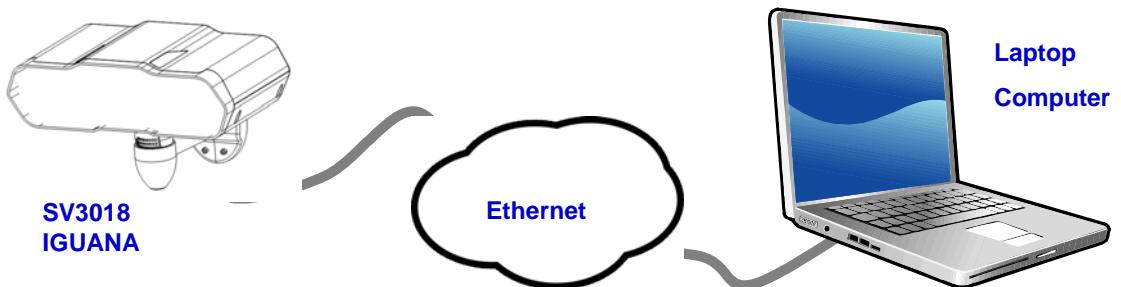
SV5100 Installation Tool v3.1 supports all kinds of IGUANA camera modules, SV2018/SV4018 and SV3018. For SV2018 or SV4018 product initial installation configuration, please refer to **Section 3.1**. For SV3018, please refer to **Section 3.2**.

3.1 SV2018/SV4018 Initial Installation using SV2010



Please refer above picture and make sure the configuration is correct

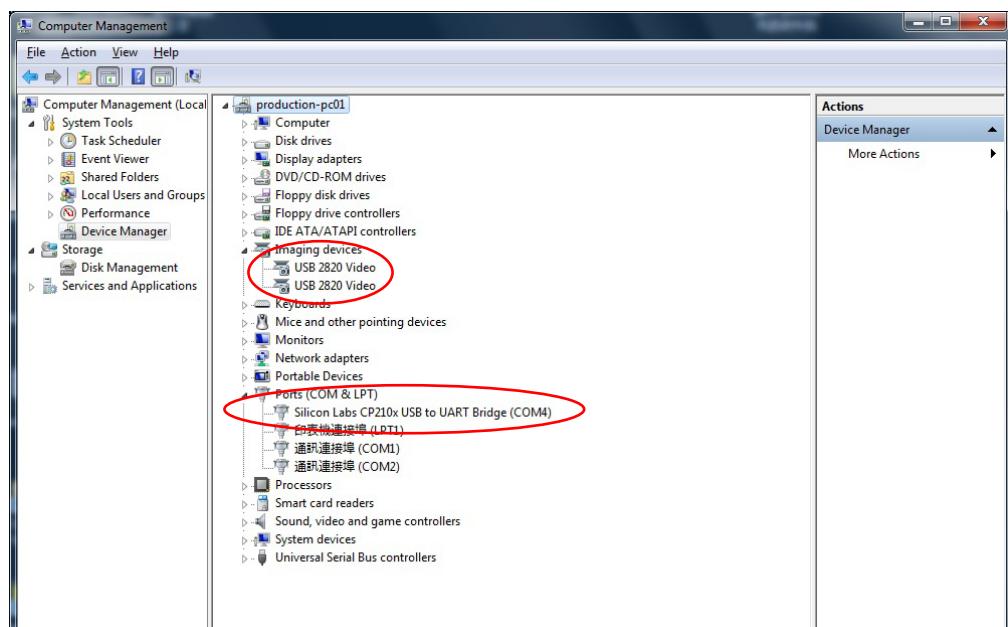
3.2 SV3018 configuration for initial installation



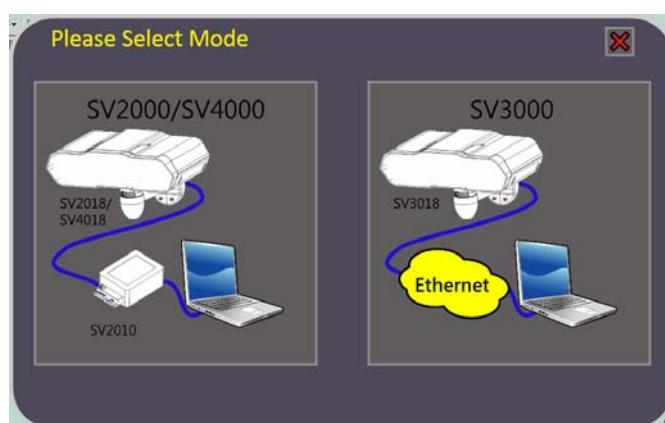
3.3 Install SV5100 Software Tool on PC or notebook

SV5100 supports **Windows XP/Vista/7 (32bit and 64bit)** OS system. When finishing installation, plug the SV2010 USB connector into PC. Check hardware device manager in the system.

There should be two “**USB 2820 Video**” under “**Imaging devices**” and one COM (“**Silicon Labs CP210x USB to UART Bridge**” or “**Prolific USB-to-Serial Comm Port**” under “**Ports**”



3.4 Execute the SV5100 Program



Select the mode according the camera model (SV2018/SV4018 or SV3018)
Please connect the IGUANA before starting the program.

3.5 System Setup

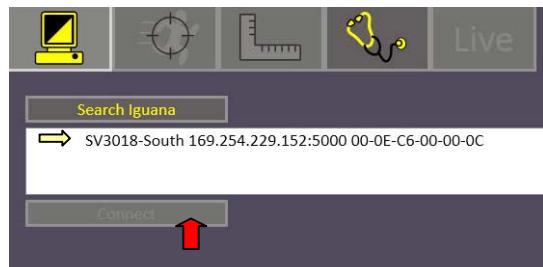
3.5.1 SV2000/SV4000 Mode



The program will search IGUANA automatically. If no device appears, double check the configuration. Please refer **Section3.1**.

3.5.2 SV3000 Mode

The program will search SV3018 automatically. If no device appears, click **Search IGUANA** again.



If no device appears, please make sure the camera module is powered on and check the network connection. (The SV3018 takes around one minute to start after power on)

Choose the IGUANA you want to setup and click **Connect**.



Check the IP setting of SV3018 which has one control unit IP and two camera IP addresses. The default IP and static IP of control unit address is 192.168.0.3.

3.6 Tracking Setup

To optimize tracking function, the following parameters including masking and other functions can be adjusted. Proper adjustments can reduce miss-firing and offer improved image quality and tracking efficiency.



A、 : Object Size

Setting the minimum target size for motion detection. The setting size is from 4pixel to 1600pixel. Selecting small target size will detect more keenly, but the miss-firing rate would also be higher.

B、 : Sensitivity

Sensitivity to trigger tracking. The sensitivity must be reduced when the miss-firing rate is high.

C、Mask Draw Area :



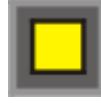
: Section

Cut the screen into two sections



: Polygon

Draw a polygon on the screen



: Rectangle

Draw a Rectangle on the screen

D、Masked Area Priority



: Normal Priority

Normal detection area. A masked area can be removed by assigning back to normal detection area.



: Half Priority
Low priority detection area



: Zero Priority
Targets within this area will not be detected

E、Delete Line



: Delete Line
Delete one line group



: Delete All Lines
Delete all lines on this screen



F、 : Default Position

The telescopic camera will return to the default position after 15 seconds of no motion detected.



G、 : Vertical Offset

Vertical fine adjustment of targets. Upward is positive.



H、 : Horizontal Offset

Horizontal fine adjustment of targets. Rightward is positive.



I、 : Lead distance

Predict the location of targets by assigning a leading movement.



J、 : Track Speed(times/sec)

Set the target tracking frequency.

K、Enable Dynamic Mask

Dynamic mask will temporary mask off the last target area to increase the probability capturing the next moving target . This function greatly improves the 'hit rate' of all moving targets.

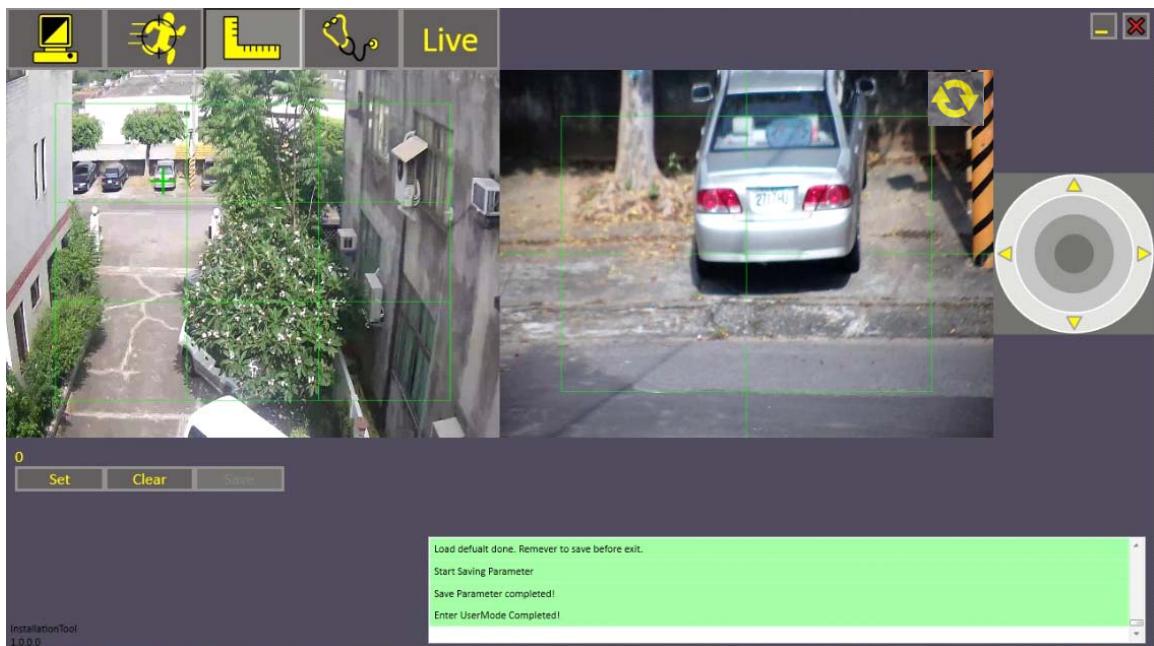
L、Distance Weight Adjustment

The image size of a target is proportional to the distance between the target and the camera. The further the target, the smaller the image is. Distance weight function will correct this effect so that all targets will have equal opportunity to be tracked regardless of the positions of the targets.

Default distance weight setting is 3. The smaller the weight, the less the adjustment will be. The maximum weight is 4.

Dynamic masking and distance weight can significantly improve the tracking efficiency of SV3018, about 10% to 20%. We strongly recommend enabling both functions.

3.7 Calibration



A、Wide-angle view (Left side)

B、Telescopic view (Right side)

(If the wide angle view and telescopic view are in wrong order, switch view at the

 system page)

C、Control panel

Adjust the direction of telescopic camera. Outer ring for larger movement and inner ring for smaller movement.

D、 Refresh camera video streams

Restart the video when either image hangs.

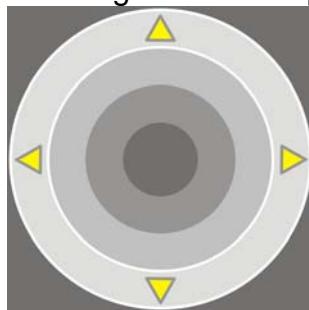
How to Use

Step 1. Choose the Calibration Point

Click on the Calibration Point on the wide angle view by using the left mouse button. The target must have a distinct feature such as a chair, air conditioner, window, tire, or a head light of a car etc. It is better to select a corner of the object, to improve calibration accuracy.

Step 2. Aim at the Calibration Point

Use the control panel to aim the center cross of the Telescopic Camera View to the Calibration Point. The control panel has eight directions: up, down, left, right, upper-left, upper-right, lower-left, lower-right in four step sizes.



Step 3. Complete the first Calibration Point

When the center cross of the Telescopic Camera View aligns with the Calibration Point of the Wide Angle Camera View, press the set button. The first Calibration Point is done.

The Calibration Point can also be moved without moving the mirror by right clicks on the wide angle view.

Step 4. Repeat Step 1~3

Repeat Step1~3 until all 9 Calibration Points are completed with OK.

Notice: Calibration Points are better positioned in every one of all 9 blocks, Up to 2 Calibration Points maximum in one block. Calibration Points should not be too close to the edge.

Step 5. Test

Click on the Wide Angle Camera View randomly, and see if the target is in the center of the telescopic camera view. If the target is too far from the desired location, redo the calibration all over again.

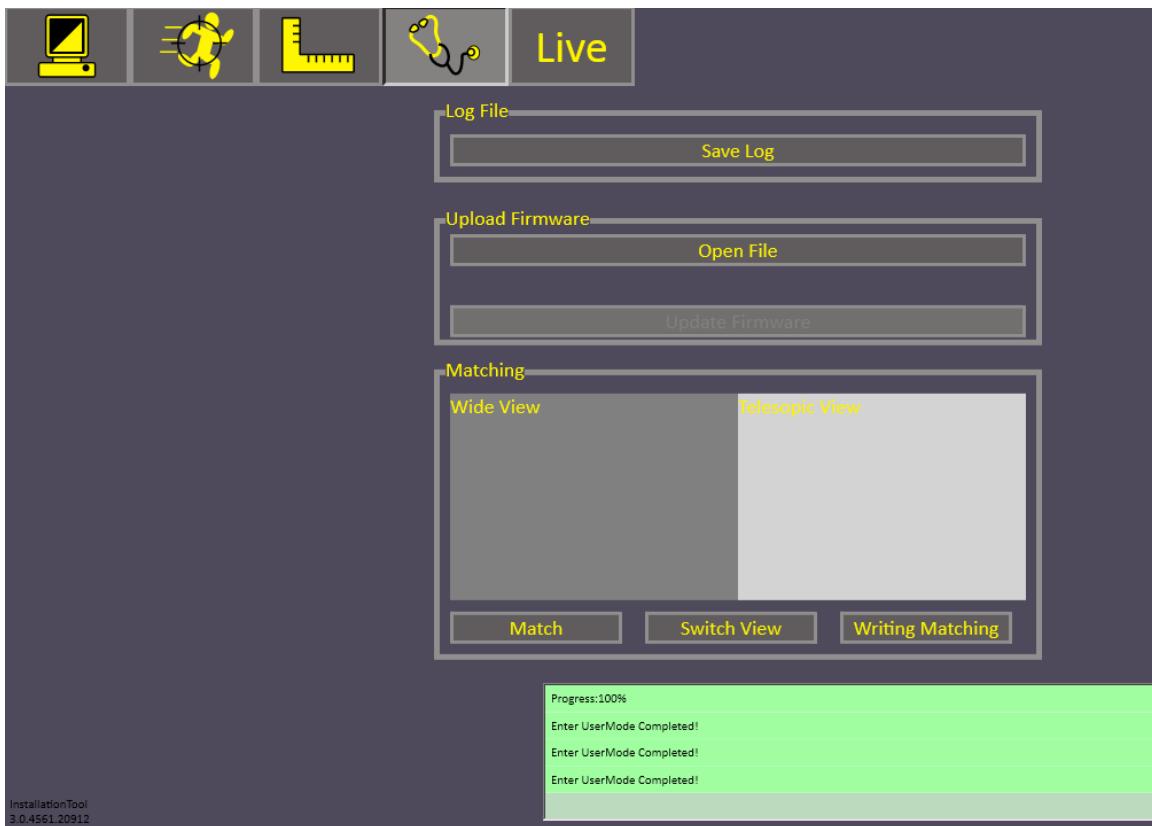
Step 6. Save Settings

If calibration is done properly, Click the save button to complete.

Step 7. Test Again

Click on the Wide Angle Camera View randomly, and see if the target is in the center of the telescopic camera view, If the target is too far from the center of the telescopic camera view, redo step 1~6.

3.8 Misc.



A、Save Log

Save the log file to NB or PC. Send this log file to Sunvision for further diagnosis.

B、Update Firmware

Update the firmware of the intelligent surveillance processor (ISP). Open the hex file which you want to update and chose OK to update the firmware.

This will takes around 5 minutes.

C、Matching

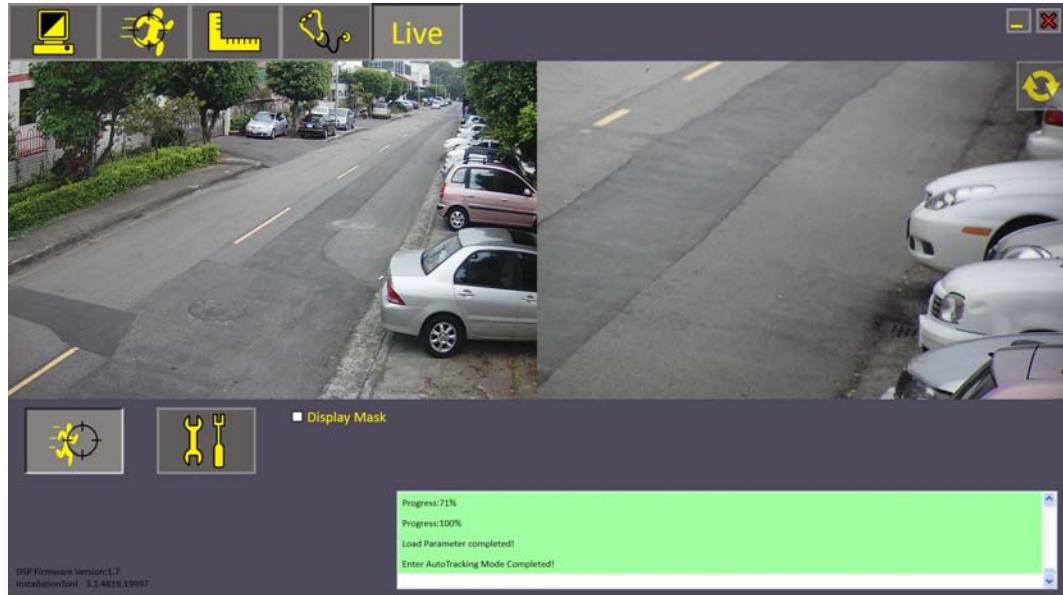
The function is used when IP cameras or IP control unit are replaced only.

Live

Live



This page shows the live view of IGUANA. Click button to enter the auto tracking mode to see the live tracking. When videos freeze or blur, please refresh .



User mode: Click on the Wide Angle view randomly, and get clear and enlarged image on telescopic view.